Installation and further use of a CANbus/LMB based Measurement System at the ATLAS ID cooling laboratory.

By Heidi Sandaker

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- Presentation of the test done at the ATLAS ID cooling laboratory. Cooling rig Example of tests
- * Why we need the CAN bus-LMB system.
- Realization of the first data acquisition system based on CAN-LMB. Presentation of the different sensors CAN bus Data acquisition program
 Tests of this first DA-system
- * Tests of this first DA-system
 - Presentation of the structure to be tested Results
- * Future development of the DA-system
 - Structures to be tested (Phase 2)
 - Number and types of sensors
 - Other aspects

Why do we need a CAN-bus/LMB based measurement system

- Cheap solution needed
 Large number of sensors
 Two wire read out possible for temperature sensors
- * High reliability

- Robust concerning Magnetic fields Radiation
- * Noisy environnement
- ✤ Real time

CAN-bus & LMB based measurement system



LMB 64 ch:TemperatureLMB ADC:Pressure (0-10V)WAGO:Valve controlPt-100, 4 wire read outMass flow (0-10V)Heater controlValve StatusHeater statusHeater status(Sonar Gas analyzer) etc..

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Measurement System

Sensor type	No	Туре	Name	LMB	V range (V)	I (A)	Comments
Temperature	64	AI	Pt-100	PT-100	+/-0.1	100p	4 wire read or
Pressure	0-8	AI	RS	ADC+ V div.	0-10	100ì	Max current
		AI	ST	ADC+ V div.	0-10	100ì	Max current
Mass flow	0-8	AI	BH	ADC+ V div.	0-10	ins.	For big rig
		AI	S	ADC	0-5	ins.	For little rig
Isolation valve control	4	DO	HW	WAGO	5 (TTL)	5m	Controlling pressurised at
Heater Control	4	DO	Custom (TTL)	WAGO	5 (TTL)	5m	Turns heater On/off
Isolation valve status	8	DI	Custom (TTL)	ADC	0-5 (TTL)	5m	Using AI
Heater status	0	DI	Custom (TTL)	ADC	0-5 (TTL)	5m	Using AI



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CAN-bus & LMB based measurement system

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Data Acquisition program



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Table of sensors:

Sensor type	No	Туре	Name	LMB	V range (V)	I (A)	Comments
Temperature	384	AI	Pt-1000	ADC + termin.	+/-0.1	100p	2 wire read out
Pressure	32+	AI	?	ADC	0-10		
Pressure control	16	AO	Н	WAGO	0-10	100ì	Via analog compressed air
Mass flow metering	1	AI	?	ADC	?	?	
Mass flow control	16	AO	Н	WAGO	0-10	100ì -	Via analog compressed air
Isolation valve control	32	DO	HW	WAGO	5 (TTL)	5m	Controlling pressurised air
Heater Control	44	DO	Custom (TTL)	WAGO	5 (TTL)	5m	Turns heaters On/off
Isolation valve status	32	DI	Custom (TTL)	ADC	0-5 (TTL)	5m	Using AI LMB
Heater status	44	DI	Custom (TTL)	ADC	0-5 (TTL)	5m	Using AI LMB

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Examples of tests made at the cooling laboratory



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Needle valv

Capillary

PT1

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Placement of the sensors in ATLAS



Structure to be tested

Layer	R (cm)	No Elements	Power /element	Manifold Factor	Elements /group	Power /group	
SCT No.4	54	56	120 W	2 series/	8	480 W	
		(staves)		2 parallel	(2 mflds)	x 2	
		10		(4 staves)			
SCT No.3	46	48	120 W	28+2P	8	480 W	
		(staves)		(4 staves)	(2 mflds)	X 2	
SCT No.2	38	40	120 W	2S+2P	4	480 W	
		(staves)		(4 staves)	(1 mfld)	x 1	
SCT No.1	30	32	120 W	2S+2P	4	480 W	
		(staves)		(4 staves)	(1 mfld)	x 1	
SCT	-	4	330 W	Quadrant	1	330 W	
Disk		(Quad- rants)				x 1	
Pixel	14	56	101 W	2	7	202 W	
No. 2		(staves)			(4pairs)	x 4	
Pixel	11	44	101 W	2	6	202 W	
No. 1		(staves)			(3pairs)	x 3	
Pixel		18	143 W	1	2	143 W	
B Layer	4.5	(staves)			(indiv.)	x 2	
Pixel	-	12	55 W	2	2	110 W	
Disk		(sectors)			(1 pair)	x 1	
TOTAL POWER (EXC. SCREENS, LOW MASS POWER RIBBONS)							

Phase 2:

1/8 of SCT and Pixel layers

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Example of small rig measurements





Test of ADC module:

- Observed error of 18% of the values read by an LMB ADC. This number is independent of ADC range chosen.

- All the channels on one board have the same error, but it varies from board to board. (Each 16 channels).



First test

Temperature distribution at room temperature of the new RAL structure. No calibration.



The first test:

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